

MATH20222: Introduction to Geometry

Sheet 4 — Semester 2 2020-21

Key exercises:

1. Calculate the area of the parallelogram $\square(\mathbf{a}, \mathbf{b})$, formed by the following vectors, where $(\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ is an orthonormal basis.
 - (a) $\mathbf{a} = 2\mathbf{e}_1 + 2\mathbf{e}_2 + 3\mathbf{e}_3$ and $\mathbf{b} = \mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3$;
 - (b) $\mathbf{a} = 5\mathbf{e}_1 + 8\mathbf{e}_2 + 4\mathbf{e}_3$ and $\mathbf{b} = 10\mathbf{e}_1 + 16\mathbf{e}_2 + 8\mathbf{e}_3$.
2. Let $\mathcal{B} = (\mathbf{e}_1, \mathbf{e}_2)$ be an orthonormal basis for \mathbb{E}^2 and let P be a linear operator with the matrix: $[P]_{\mathcal{B}} = \begin{bmatrix} 5 & -1 \\ 2 & 2 \end{bmatrix}$. (See Exercise Sheet 2 Q3.)
 - (a) Calculate the area of the parallelogram $\square(\mathbf{e}_1 + \mathbf{e}_2, \mathbf{e}_1 + 2\mathbf{e}_2)$.
 - (b) Recall the $\mathbf{a} = \mathbf{e}_1 + \mathbf{e}_2$ is an eigenvector of P with eigenvalue 4; and $\mathbf{b} = \mathbf{e}_1 + 2\mathbf{e}_2$ is an eigenvector of P with eigenvalue 3. Calculate the area of the image parallelogram $\square(P(\mathbf{a}), P(\mathbf{b}))$.
 - (c) Compare your answers to parts (a) and (b) with the $\det P$.
3. Let $\mathcal{B} = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ be an orthonormal basis for \mathbb{E}^3 . Let P be the linear operator with matrix $[P]_{\mathcal{B}} = \begin{bmatrix} 1 & 3 & -4 \\ 2 & 4 & -4 \\ 0 & 0 & 1 \end{bmatrix}$.
 - (a) Calculate the volume of the parallelepiped formed by the vectors $\mathbf{a} = 2\mathbf{e}_1 + \mathbf{e}_3$; $\mathbf{b} = 4\mathbf{e}_2 + 3\mathbf{e}_3$; and $\mathbf{c} = \mathbf{e}_1 - \mathbf{e}_2$.
 - (b) Calculate $P(\mathbf{a})$, $P(\mathbf{b})$ and $P(\mathbf{c})$.
 - (c) What is the volume of the parallelepiped $\text{vol}(\square(P(\mathbf{a}), P(\mathbf{b}), P(\mathbf{c})))$?
 - (d) Compare the volumes from parts (a) and (c) with the determinant of P .

Extra exercises:

4. Let $\mathcal{B} = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ be an orthonormal basis in \mathbb{E}^3 . Find a unit vector \mathbf{n} , such that the following conditions hold:
1. \mathbf{n} is orthogonal to $\mathbf{a} = \mathbf{e}_1 + 2\mathbf{e}_2 + 3\mathbf{e}_3$;
 2. \mathbf{n} is orthogonal to $\mathbf{b} = \mathbf{e}_1 + 3\mathbf{e}_2 + 2\mathbf{e}_3$;
 3. The basis $(\mathbf{a}, \mathbf{b}, \mathbf{n})$ has an orientation opposite to \mathcal{B} .

Express \mathbf{n} using the basis \mathcal{B} .

5. Elisa and Faraz calculate the vector product of two vectors \mathbf{a} and \mathbf{b} in \mathbb{E}^3 . Elisa uses the orthonormal basis $\mathcal{E} = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ and Faraz use the orthonormal basis $\mathcal{F} = (\mathbf{f}_1, \mathbf{f}_2, \mathbf{f}_3)$. The vectors expressed in these bases are:

$$[\mathbf{a}]_{\mathcal{E}} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \quad [\mathbf{b}]_{\mathcal{E}} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \quad [\mathbf{a}]_{\mathcal{F}} = \begin{bmatrix} a'_1 \\ a'_2 \\ a'_3 \end{bmatrix} \quad [\mathbf{b}]_{\mathcal{F}} = \begin{bmatrix} b'_1 \\ b'_2 \\ b'_3 \end{bmatrix}$$

They both use the *determinant formula* for calculations:

$$\mathbf{a} \times \mathbf{b} \stackrel{?}{=} \underbrace{\det \begin{bmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{bmatrix}}_{\text{Elisa's calculations}} \stackrel{?}{=} \underbrace{\det \begin{bmatrix} \mathbf{f}_1 & \mathbf{f}_2 & \mathbf{f}_3 \\ a'_1 & a'_2 & a'_3 \\ b'_1 & b'_2 & b'_3 \end{bmatrix}}_{\text{Faraz's calculations}}.$$

- (a) In what situations do their calculations give the same vector, and when do they give different answers?
- (b) In each case what can you say about the linear operator P , that maps each vector $\mathbf{e}_i \mapsto \mathbf{f}_i$?

6. Let \mathcal{B} , P , \mathbf{a} , \mathbf{b} and \mathbf{c} be as in question 3.

(a) What is the area of the parallelograms:

(i) $\sphericalangle(\mathbf{a}, \mathbf{b})$;

(ii) $\sphericalangle(\mathbf{a}, \mathbf{c})$?

(b) Compare these to the areas of the image parallelograms:

(i) $\sphericalangle(P(\mathbf{a}), P(\mathbf{b}))$;

(ii) $\sphericalangle(P(\mathbf{a}), P(\mathbf{c}))$?

(c) Can you say anything about the determinant of a linear operator acting on a 3-dimensional space and the scaling of parallelograms?

(d) Can you find a linear operator that fixes the volume of parallelepipeds but scales the area of some parallelogram by λ ?

7.† In this question we will prove the determinant formula satisfies the axioms of a vector product. Fix an orthogonal basis $\mathcal{B}(\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ for \mathbb{E}^3 , which we use to define the orientation of \mathbb{E}^3 . For any two vectors $\mathbf{v} = v_1\mathbf{e}_1 + v_2\mathbf{e}_2 + v_3\mathbf{e}_3$ and $\mathbf{w} = w_1\mathbf{e}_1 + w_2\mathbf{e}_2 + w_3\mathbf{e}_3$ define the function $-\times -: \mathbb{E}^3 \times \mathbb{E}^3 \rightarrow \mathbb{E}^3$ by the determinant formula:

$$\mathbf{v} \times \mathbf{w} = \det \begin{bmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{bmatrix}.$$

(VP-AC) Show, or explain why, $\mathbf{v} \times \mathbf{w} = -\mathbf{w} \times \mathbf{v}$ for all vectors \mathbf{v} and \mathbf{w} .

(VP-⊥) (i) Show that $\langle \mathbf{v} \times \mathbf{w}, \mathbf{v} \rangle = 0$ for all vectors \mathbf{v} and \mathbf{w} .

(ii) Using (VP-AC) deduce that $\langle \mathbf{v} \times \mathbf{w}, \mathbf{w} \rangle = 0$.

(VP-Lin) (i) Show the following identity holds:

$$\det \begin{bmatrix} \lambda a + \mu a' & \lambda b + \mu b' \\ c & d \end{bmatrix} = \lambda \det \begin{bmatrix} a & b \\ c & d \end{bmatrix} + \mu \det \begin{bmatrix} a' & b' \\ c & d \end{bmatrix}.$$

(ii) Prove that $(\lambda\mathbf{v} + \mu\mathbf{w}) \times \mathbf{x} = \lambda(\mathbf{v} \times \mathbf{x}) + \mu(\mathbf{w} \times \mathbf{x})$ for all vectors \mathbf{v}, \mathbf{w} and \mathbf{x} .

(VP-Len) Recall the identity of Lemma 1.83: $|\mathbf{v} \times \mathbf{w}|^2 + \langle \mathbf{v}, \mathbf{w} \rangle^2 = |\mathbf{v}|^2|\mathbf{w}|^2$.

Using this formula, or otherwise, prove $|\mathbf{v} \times \mathbf{w}| = |\mathbf{v}||\mathbf{w}|$ for all perpendicular vectors \mathbf{v} and \mathbf{w} .

(VP-O) Let $v_1\mathbf{e}_1 + v_2\mathbf{e}_2 + v_3\mathbf{e}_3$ and $\mathbf{w} = w_1\mathbf{e}_1 + w_2\mathbf{e}_2 + w_3\mathbf{e}_3$, be linearly independent vectors.

(i) Let $\mathcal{C} = (\mathbf{v}, \mathbf{w}, \mathbf{v} \times \mathbf{w})$, which you may assume is a basis for \mathbb{E}^3 . Write down the transition matrix T , from basis \mathcal{B} to basis \mathcal{C} .

(ii) Calculate a formula for the determinant of T and deduce that \mathcal{B} and \mathcal{C} have the same orientation.

It may be helpful to use the 3rd column to calculate the determinant:

$$\det \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = c \det \begin{bmatrix} d & e \\ g & h \end{bmatrix} - f \det \begin{bmatrix} a & b \\ g & h \end{bmatrix} + i \det \begin{bmatrix} a & b \\ d & e \end{bmatrix}.$$

Finally: Deduce that $-\times -$ is a vector product as defined in Definition 1.77.